# The $q$-deformed heat equation and $q$-deformed diffusion equation with $q$-translation symmetry 

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In this paper we consider the discrete heat equation with a certain non-uniform space interval which is related to $q$-addition appearing in the non-extensive entropy theory. By taking the continuous limit, we obtain the $q$-deformed heat equation. Similarly, we obtain the solution of the $q$-deformed diffusion equation.

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## 1. Introduction

Heat equation governs how heat diffuses or transfers through a region, which was first introduced by Fourier [1] in 1822. In one dimension, this equation take the form,

$$
\begin{equation*}
\frac{\partial}{\partial t} u(x, t)=\kappa\left(\frac{\partial}{\partial x}\right)^{2} u(x, t) \tag{1}
\end{equation*}
$$

where $u(x, t)$ is the temperature at position $x$ at time $t$ and $\kappa$ is thermal diffusivity.

In this paper we are to find a deformed heat equation. To do so we need the discrete version of heat equation where space is discrete but time is continuous. Discrete physics have been studied in various fields [2-15]. If we consider discrete positions denoted by

$$
\begin{equation*}
x_{n}=n a, \quad n \in \mathbb{Z} \tag{2}
\end{equation*}
$$

we have the discrete heat equation,

$$
\begin{equation*}
\frac{\partial}{\partial t} u\left(x_{n}, t\right)=\kappa \Delta_{x}^{2} u\left(x_{n}, t\right) \tag{3}
\end{equation*}
$$

where finite difference operators are defined as

$$
\begin{equation*}
\Delta_{x} u\left(x_{n}, t\right)=\frac{u\left(x_{n+1}, t\right)-u\left(x_{n}, t\right)}{a} \tag{4}
\end{equation*}
$$

If we take the limit $a \rightarrow 0$ in Eq. (4), we have Eq. (1). From Eq. (2), we know that

$$
\begin{equation*}
x_{n+1}-x_{n}=a, \tag{5}
\end{equation*}
$$

which implies that the uniform space interval guarantees the heat equation of the form (1). In other words, if we consider a non-uniform discrete position, we will obtain another form of heat equation.

In this paper we consider the discrete heat equation with a certain non-uniform space interval which is related to $q$ addition or $q$-subtraction appearing in the non-extensive entropy theory [16-18]. By taking the continuous limit, we obtain the $q$-deformed heat equation. Similarly, we derive the $q$-deformed diffusion equation. This paper is organized as follows: In Sec. 2 we discuss the $q$-deformed heat equation. In Sec. 3 we discuss the solution of $q$-deformed heat equation. In Sec. 4 we discuss cooling of a rod from a constant initial temperature. In Sec. 5 we discuss the $q$-deformed diffusion equation.

## 2. $q$-deformed heat equation

In this section we discuss the $q$-deformed heat equation based on the the $q$-addition and $q$-subtraction appearing in the nonextensive thermodynamics [16-18]. As is different from the non-extensive thermodynamics, we introduce the parameter $q$ so that it may have a dimension of inverse length. In the nonextensive thermodynamics, the parameter $q$ is dimensionless. Thus, in the $q$-deformed heat equation, $q$ can be regarded as $1 / \xi$ where $\xi$ denotes a length scale.

Now let us introduce the discrete position with nonuniform interval where the distance between adjacent positions are given by

$$
\begin{equation*}
x_{n+1} \ominus_{q} x_{n}=a \tag{6}
\end{equation*}
$$

or

$$
\begin{equation*}
x_{n+1}=x_{n} \oplus_{q} a \tag{7}
\end{equation*}
$$

where the $q$-addition and $q$-subtraction [16-18] are defined as

$$
\begin{align*}
& a \oplus_{q} b=a+b+q a b,  \tag{8}\\
& a \ominus_{q} b=\frac{a-b}{1+q b} . \tag{9}
\end{align*}
$$

As is different from the uniform lattice, the non-uniform lattice consisting discrete points obeying Eq. (6) can be regarded as an example of the non-homogeneous medium in the continuous limit ( $a \rightarrow 0$ ). We think that the discrete positions defined by the different pseudo addition (deformation of the ordinary addition) can give another examples of the non-homogeneous medium in the continuous limit. For example, in Ref. [19], the $\alpha$-addition was introduced to describe the non-homogeneous medium where anomalous diffusion arose.

The Eq. (6) gives the relation

$$
\begin{equation*}
x_{n+1}=(1+q a) x_{n}+a \tag{10}
\end{equation*}
$$

Solving Eq. (10) we get

$$
\begin{equation*}
x_{n}=\frac{1}{q}\left([1+q a]^{n}-1\right), \tag{11}
\end{equation*}
$$

When $q>0$ we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} x_{n}=\infty \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{n \rightarrow-\infty} x_{n}=-\frac{1}{q} \tag{13}
\end{equation*}
$$

When $q<0$ we get

$$
\begin{equation*}
\lim _{n \rightarrow \infty} x_{n}=\frac{1}{|q|} \tag{14}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{n \rightarrow-\infty} x_{n}=-\infty \tag{15}
\end{equation*}
$$

In this case we demand $|q| a<1$. The discrete position is not symmetric for $x_{0}=0$. Indeed, we have

$$
\begin{equation*}
x_{-n}=-\frac{x_{n}}{(1+q a)^{n}}, \quad n \geq 1 \tag{16}
\end{equation*}
$$

For the discrete positions obeying Eq. (6), the difference operator becomes

$$
\begin{align*}
\Delta_{x: q} u\left(x_{n}, t\right) & =\frac{u\left(x_{n+1}, t\right)-u\left(x_{n}, t\right)}{x_{n+1} \ominus_{q} x_{n}}=\left(1+q x_{n}\right) \\
& \times\left(\frac{u\left(x_{n+1}, t\right)-u\left(x_{n}, t\right)}{x_{n+1}-x_{n}}\right) \tag{17}
\end{align*}
$$

Thus, in the continuum limit, we get

$$
\begin{equation*}
\Delta_{x: q} u\left(x_{n}, t\right) \rightarrow D_{x}^{q}=(1+q x) \frac{\partial u}{\partial x} \tag{18}
\end{equation*}
$$

Here we know that the $q$-derivative $D_{x}^{q}$ remains invariant under the $q$-translation $x \rightarrow x \oplus \delta x$. Recently, quantum theory with $q$-translation invariance was constructed in [20]. Using Eq. (18), we obtain the $q$-deformed heat equation with $q$-translation symmetry in the form,

$$
\begin{equation*}
\frac{\partial}{\partial t} u(x, t)=\kappa\left(D_{x}^{q}\right)^{2} u(x, t) \tag{19}
\end{equation*}
$$

## 3. Solution of $q$-deformed heat equation

Consider a rod of length $L$ with the initial condition

$$
\begin{equation*}
u(x, 0)=f(x) \tag{20}
\end{equation*}
$$

and the boundary condition

$$
\begin{equation*}
u(0, t)=u(L, t)=0 \tag{21}
\end{equation*}
$$

We look for a solution of the form

$$
\begin{equation*}
u(x, t)=X(x) T(t) \tag{22}
\end{equation*}
$$

Inserting Eq. (22) into Eq. (19) we get

$$
\begin{equation*}
\frac{1}{\kappa T} \frac{d T}{d t}=\frac{1}{X}\left(D_{x}^{q}\right)^{2} X=-\lambda, \quad \lambda>0 \tag{23}
\end{equation*}
$$

Thus, we have

$$
\begin{equation*}
T(t)=e^{-\kappa \lambda t} \tag{24}
\end{equation*}
$$

and

$$
\begin{align*}
X(x) & =A \cos \left(\frac{\sqrt{\lambda}}{q} \ln (1+q x)\right) \\
& +B \sin \left(\frac{\sqrt{\lambda}}{q} \ln (1+q x)\right) \tag{25}
\end{align*}
$$

From the boundary function, we have $A=0$ and

$$
\begin{equation*}
\sin \left(\frac{\sqrt{\lambda}}{q} \ln (1+q L)\right)=0 \tag{26}
\end{equation*}
$$

which gives

$$
\begin{equation*}
\sqrt{\lambda}=\lambda_{n}=\frac{q n \pi}{\ln (1+q L)}, \quad n=1,2, \cdots \tag{27}
\end{equation*}
$$

Thus, the general solution of $q$-deformed wave equation is

$$
\begin{align*}
u(x, t) & =\sum_{n=1}^{\infty} B_{n} \sin \left(n \pi \frac{\ln (1+q x)}{\ln (1+q L)}\right) \\
& \times \exp \left(-\frac{\kappa q^{2} n^{2} \pi^{2} t}{(\ln (1+q L))^{2}}\right) \tag{28}
\end{align*}
$$

Now let us apply the initial condition. Then we have

$$
\begin{equation*}
f(x)=\sum_{n=1}^{\infty} B_{n} \sin \left(n \pi \frac{\ln (1+q x)}{\ln (1+q L)}\right) \tag{29}
\end{equation*}
$$

If we use the orthogonality relation

$$
\begin{gather*}
\int_{0}^{L} \sin \left(n \pi \frac{\ln (1+q x)}{\ln (1+q L)}\right) \sin \left(m \pi \frac{\ln (1+q x)}{\ln (1+q L)}\right) \\
 \tag{30}\\
\times \frac{d x}{1+q x}=\frac{\ln (1+q L)}{2 q} \delta_{n m}
\end{gather*}
$$

we have

$$
\begin{align*}
B_{n} & =\frac{2 q}{\ln (1+q L)} \int_{0}^{L} f(x) \\
& \times \sin \left(n \pi \frac{\ln (1+q x)}{\ln (1+q L)}\right) \frac{d x}{1+q x} . \tag{31}
\end{align*}
$$

Here we solved the $q$-heat equation in a closed form. Our method is to introduce the $q$-lattice as an example of the nonhomogeneous medium, which is not related to the numerical solution methods based on adaptive grids [21-24] because we obtained the exact solution.

## 4. Cooling of a rod from a constant initial temperature

Suppose the initial temperature distribution $f(x)$ in the rod is constant, i.e. $f(x)=u_{0}$. Now let us consider the case of $L=1, \kappa=1$. Then we have

$$
\begin{equation*}
B_{n}=-\frac{2 u_{0}}{n \pi}\left((-1)^{n}-1\right) \tag{32}
\end{equation*}
$$

Thus, we have

$$
\begin{align*}
u(x, t) & =\frac{4 u_{0}}{\pi} \sum_{n=1}^{\infty} \frac{1}{2 n-1} \sin \left((2 n-1) \pi \frac{\ln (1+q x)}{\ln (1+q)}\right) \\
& \times \exp \left(-\frac{q^{2}(2 n-1)^{2} \pi^{2} t}{(\ln (1+q))^{2}}\right) \tag{33}
\end{align*}
$$

In this case, the ratio of the first and second terms in Eq. (33) is

$$
\begin{align*}
\frac{\mid \text { second term } \mid}{\mid \text { first term } \mid} & =\frac{1}{3} e^{-\frac{8 q^{2} \pi^{2} t}{(\ln (1+q))^{2}}} \frac{\left|\sin \left(3 \pi \frac{\ln (1+q)}{\ln (1+q)}\right)\right|}{\left|\sin \left(\pi \frac{\ln (1+q x)}{\ln (1+q)}\right)\right|}  \tag{34}\\
& \leq e^{-\frac{8 q^{2} \pi^{2} t}{\left(\ln (1+q)^{2}\right.}}  \tag{35}\\
& \leq e^{-8 \quad \text { for } t \leq t_{q}} \tag{36}
\end{align*}
$$

where we used

$$
\begin{equation*}
|\sin n t| \leq n|\sin t| \tag{37}
\end{equation*}
$$

and

$$
\begin{equation*}
t_{q}=\frac{(\ln (1+q))^{2}}{q^{2} \pi^{2}} \tag{38}
\end{equation*}
$$

Thus, the first term dominates the sum of the rest of the terms, and hence

$$
\begin{align*}
u(x, t) & \approx \frac{4 u_{0}}{\pi} \sin \left(\pi \frac{\ln (1+q x)}{\ln (1+q)}\right) \\
& \times \exp \left(-\frac{q^{2} \pi^{2} t}{(\ln (1+q))^{2}}\right) \tag{39}
\end{align*}
$$

### 4.1. Spatial temperature profiles

Now let us consider fixed time. Here we consider the time $t=t_{q}$. Then we have

$$
\begin{equation*}
u(x, t) \approx \frac{4 u_{0}}{\pi} e^{-1} \sin \left(\pi \frac{\ln (1+q x)}{\ln (1+q)}\right) \tag{40}
\end{equation*}
$$

This has the maxima at $x=x_{0}$ where

$$
\begin{equation*}
x_{0}=\frac{\sqrt{1+q}-1}{q} . \tag{41}
\end{equation*}
$$

Thus, center of a rod is not a line of symmetry unless $q=0$. Fig. 1 shows the plot of $u$ versus $x$ with $u_{0}=1$ for $q=0$ (Red), $q=0.2$ (Brown), and $q=-0.2$ (Gray). We know that the position for maximum of $u$ is smaller than $1 / 2$ for $q>0$ while it is larger than $1 / 2$ for $q<0$.

### 4.2. Temperature profiles in time

Setting $x=x_{0}$ in the approximate solution, we have

$$
\begin{equation*}
u(x, t) \approx \frac{4 u_{0}}{\pi} \exp \left(-\frac{q^{2} \pi^{2} t}{(\ln (1+q))^{2}}\right) \tag{42}
\end{equation*}
$$

Figure 2 shows the plot of $u$ versus $t$ with $u_{0}=1, x=x_{0}$ for $q=0$ (Red), $q=0.2$ (Brown), and $q=-0.2$ (Gray).


Figure 1. Plot of $u$ versus $x$ with $u_{0}=1$ for $q=0$ (Red), $q=0.2$ (Brown), and $q=-0.2$ (Gray).


Figure 2. Plot of $u$ versus $t$ with $u_{0}=1, x=x_{0}$ for $q=0$ (Red), $q=0.2$ (Brown), and $q=-0.2$ (Gray).

## 5. $q$-deformed diffusion equation

The $q$-deformed diffusion equation has the same form as the $q$-deformed heat equation,

$$
\begin{equation*}
\frac{\partial}{\partial t} u(x, t)=D\left(D_{x}^{q}\right)^{2} u(x, t) \tag{43}
\end{equation*}
$$

where $u(x, t)$ denotes the concentration and $D$ denotes diffusivity. Now let us impose the initial condition

$$
\begin{equation*}
u(x, 0)=f(x) \tag{44}
\end{equation*}
$$

Now let us introduce the $q$-deformed Fourier transform as

$$
\mathcal{F}(u(x, t))=U(w, t)=\left\{\begin{array}{cc}
\frac{1}{2 \pi} \int_{-1 / q}^{\infty} \frac{d x}{1+q x} u(x, t)(1+q x)^{\frac{i w}{q}} & (q>0)  \tag{45}\\
\frac{1}{2 \pi} \int_{-\infty}^{1 /|q|} \frac{d x}{1+q x} u(x, t)(1+q x)^{\frac{i w}{q}} & (q<0)
\end{array}\right.
$$

and the inverse $q$-deformed Fourier transform

$$
\begin{equation*}
\mathcal{F}^{-1}(U(w, t))=u(x, t)=\int_{-\infty}^{\infty} d w U(w, t)(1+q x)^{-\frac{i w}{q}} \tag{46}
\end{equation*}
$$

From the definition of $q$-deformed Fourier transform, we know

$$
\begin{equation*}
\mathcal{F}\left(\left(D_{x}^{q}\right)^{n} u(x, t)\right)=(-i w)^{n} U(w, t) \tag{47}
\end{equation*}
$$

Taking the $q$-deformed Fourier transform in Eq. (43) we get

$$
\begin{equation*}
\frac{\partial U(w, t)}{\partial t}=-D w^{2} U(w, t) \tag{48}
\end{equation*}
$$

which is solved as

$$
\begin{equation*}
U(w, t)=c(w) e^{-D w^{2} t} \tag{49}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
U(w, 0)=c(w) \tag{50}
\end{equation*}
$$

Thus we get

$$
\begin{equation*}
c(w)=\mathcal{F}(f(x)) \tag{51}
\end{equation*}
$$

Now let us set

$$
\begin{equation*}
g(x)=\mathcal{F}^{-1}\left(e^{-D w^{2} t}\right) \tag{52}
\end{equation*}
$$

which gives

$$
\begin{equation*}
g(x)=\sqrt{\frac{\pi}{D t}} \exp \left(-\frac{1}{4 D t}\left[\frac{1}{q} \ln (1+q x)\right]^{2}\right) \tag{53}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
U(w, t)=\mathcal{F}(f(x)) \mathcal{F}(g(x)) \tag{54}
\end{equation*}
$$

From the convolution theorem we get

$$
u(x, t)= \begin{cases}\frac{1}{2 \pi} \int_{-1 / q}^{\infty} \frac{d x}{1+q x} f(s) g\left(\frac{1}{q} \ln \left(\frac{1+q x}{1+q s}\right)\right) & (q>0)  \tag{55}\\ \frac{1}{2 \pi} \int_{-\infty}^{1 /|q|} \frac{d x}{1+q x} f(s) g\left(\frac{1}{q} \ln \left(\frac{1+q x}{1+q s}\right)\right) & (q<0)\end{cases}
$$

If we impose the initial condition

$$
\begin{equation*}
f(x)=\delta(x) \tag{56}
\end{equation*}
$$

we have

$$
\begin{equation*}
u(x, t)=\frac{1}{\sqrt{4 \pi D t}} \exp \left(-\frac{1}{4 D t}\left[\frac{1}{q} \ln (1+q x)\right]^{2}\right) \tag{57}
\end{equation*}
$$

From Eq. (57), the expectation value of $x$ are

$$
\begin{equation*}
E(x)=\frac{1}{q} e^{q^{2} D t}\left(e^{3 q^{2} D t}-1\right) \tag{58}
\end{equation*}
$$

For a small $q$, we get

$$
\begin{equation*}
E(x) \approx 3 q D t \tag{59}
\end{equation*}
$$

The variance is then given by

$$
\begin{align*}
V(x) & =-\frac{2}{q^{2}} e^{5 q^{2} D t}\left(\cosh \left(q^{2} D t\right)+\cosh \left(3 q^{2} D t\right)\right. \\
& \left.-\cosh \left(4 q^{2} D t\right)-\sinh \left(q^{2} D t\right)-1\right) \tag{60}
\end{align*}
$$

For a small $q$, we get

$$
\begin{equation*}
V(x) \approx 2 D t+16 q^{2}(D t)^{2} \tag{61}
\end{equation*}
$$

Figure 3 shows the plot of $u(x, t)$ versus $x$ with $t=1$ and $D=1$ for $q=0$ (Pink), $q=0.2$ (Brown) and $q=-0.2$ (Gray). We know that the graph is asymmetric unless $q=0$. Thus Eq. (57) is the asymmetric normal distribution. Figure 4 shows the plot of $u(x, t)$ versus $x$ with $q=0.2$ and $D=1$ for $t=1$ (Pink), $t=2$ (Brown) and $t=3$ (Gray). Figure 5 shows the plot of $u(x, t)$ versus $x$ with $q=-0.2$ and $D=1$ for $t=1$ (Pink), $t=2$ (Brown) and $t=3$ (Gray).


Figure 3. Plot of $u(x, t)$ versus $x$ with $t=1$ and $D=1$ for $q=0$ (Pink), $q=0.2$ (Brown) and $q=-0.2$ (Gray).


Figure 4. Plot of $u(x, t)$ versus $x$ with $q=0.2$ and $D=1$ for $t=1$ (Pink), $t=2$ (Brown) and $t=3$ (Gray).


Figure 5. Plot of $u(x, t)$ versus $x$ with $q=-0.2$ and $D=1$ for $t=1$ (Pink), $t=2$ (Brown) and $t=3$ (Gray).

## 6. Conclusion

In this paper we studied the $q$-deformed heat equation and $q$-deformed diffusion equation. From the fact that the ordinary heat equation was obtained by taking continuous limit in the discrete heat equation with a uniform space interval, we considered the discrete heat equation with a certain nonuniform space interval which was related to $q$-addition or $q$ subtraction appearing in the non-extensive thermodynamics.

By taking the continuous limit, we obtained the $q$-deformed heat equation. We found that the $q$-deformed heat equation possessed the $q$-translation symmetry instead of the ordinary translation. We solved the $q$-deformed heat equation for a rod of length $L$. We discussed cooling of a rod from a constant initial temperature. We used the $q$-deformed Fourier transform to find the solution of the $q$-deformed diffusion equation. We found that the variance in $x$ takes the form,

$$
\begin{align*}
V(x) & =-\frac{2}{q^{2}} e^{5 q^{2} D t}\left(\cosh \left(q^{2} D t\right)+\cosh \left(3 q^{2} D t\right)\right. \\
& \left.-\cosh \left(4 q^{2} D t\right)-\sinh \left(q^{2} D t\right)-1\right) \tag{62}
\end{align*}
$$

For a small $q$, we obtained

$$
\begin{equation*}
V(x) \approx 2 D t+16 q^{2}(D t)^{2} \tag{63}
\end{equation*}
$$

We found that the $q$-deformed diffusion process is asymmetric.

The $q$-addition and $q$-subtraction defined in the nonextensive thermodynamics was rarely used in the deformation of the space-time ( $q$-deformed space time). The application to quantum mechanics was discussed in Ref. [20], application to mechanics was discussed in Ref. [25], and construction of $q$-lattice and $q$-Bloch theorem was discussed in Ref. [26].

Besides, we comment the connection of nonhomogeneous media with the $q$-deformation of space briefly. It seems impossible to describe the general nonhomogeneous media in an exact way without numerical study. Here, we adopted a special non-homogeneous media related to $q$-deformed space. Because asymmetry of the $q$-lattice, the graphs of temperature in the $q$-heat equation and concentration in the $q$-deformed equation became asymmetric, which had different feature for positive $q$ and negative $q$, (See Fig. 1-5).

Finally, we compare the $q$-deformed diffusion equation with the diffusion model with the effective position dependent diffusion coefficient $\mathcal{D}(x)$ [27-29]. The diffusion equation with the effective position dependent diffusion coefficient $\mathcal{D}(x)$ was given in the form,

$$
\begin{equation*}
\frac{\partial u(x, t)}{\partial t}=\frac{\partial}{\partial x}\left(w(x) \mathcal{D}(x) \frac{\partial}{\partial x}\left[\frac{u(x, t)}{w(x)}\right]\right) \tag{64}
\end{equation*}
$$

where $w(x)$ denotes the variable cross section. Comparing Eq. (43) with Eq. (64), we know

$$
\begin{equation*}
w(x)=1+q x, \quad \mathcal{D}(x)=D(1+q x)^{2} . \tag{65}
\end{equation*}
$$

Thus we know that the $q$-deformed diffusion equation is an example of the diffusion model with the effective position dependent diffusion coefficient.

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